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Technical



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OPTIMUM DYNAMIC DESIGN OF NONLINEAR

PLATES UNDER BLAST LOADING

author:

J. M. Ferritto

date:

March 1978

sponsor:

NAVAL FACILITIES ENGINEERING COMMAND

program nos: 5

51-082





CIVIL ENGINEERING LABORATORY

NAVAL CONSTRUCTION BATTALION CENTER Port Hueneme, California 93043

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Civil Engineering Laboratory

OPTIMUM DYNAMIC DESIGN OF NONLINEAR PLATES
UNDER BLAST LOADING, by J. M. Ferritto
TN-1518 55 pp illus March 1978 Unclassified

- 1. Nonlinear structural dynamics
- 2. Blast-resistant design
- 1. 51-082

A computer program was developed to determine the approximate nonlinear dynamic response of plates subjected to blast pressure loading. Given the explosive parameters and geometry of the plate, the program computes the blast environment and the structural resistance, mass, and stiffness of the plate and solves for the dynamic response. The program contains optimization subroutines that provide for automatic optimum design of least-cost plates. The program will assist engineers in the design and analysis of blast doors that are intended to contain the effects of accidental explosions. The report gives a user's guide and sample problems with data input and program output.

Unclassified

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INTRODUCTION

The Department of Defense (DOD) has numerous facilities engaged in the production of various types of explosives and munitions used by military services. In most cases the production of ammunition utilizes assembly line procedures. Projectiles pass through various stages of preparation: filling with explosive, fuzing, marking, and packing. Hazardous operations, such as the filling of the projectile case with an explosive in a powder form and the compaction of the powder by hydraulic press, are accomplished in protective cells that are intended to confine the effects of an accidental explosion.

Most of the existing production facilities were built in the 1940s. With few exceptions, the manufacturing technology and existing equipment represent the state-of-the-art at that time. The production equipment was operated extensively during World War II, again during the Korean conflict, and recently during the Southeast Asia war. Much of this equipment and the housing structures have been operating beyond their designed capacities (Ref 1).

DOD is conducting an ammunition plant modernization program (Ref 2) intended to greatly enhance safety in the production plants by protective construction, automated processing, and reduction of the number of personnel involved in hazardous operations.

In 1969 a joint-service manual (Ref 3) was published to provide guidance to the structural designers of munition plants. The objectives of the manual were to establish design procedures and construction techniques (1) to prevent propagation of explosions from one building (or part of a building) to another, (2) to prevent mass detonations, and (3) to protect personnel and equipment. The manual establishes blastload parameters for designing protective structures, provides methods for calculating the dynamic response of concrete walls, and establishes construction details for developing required strength. The design method accounts for close-in effects of a detonation with its associated high pressures and nonuniformity of loading on protective barriers. A detailed method for assessing the degree of protection afforded by a protective facility did not exist prior to this manual's publication; consequently, the manual represents a significant improvement in design methods. The simplifications made in the development of the design procedures have been presented in the manual. The analysis of a structure using the design procedure will generally result in a conservative estimate of the structure's capacity; therefore, structures designed using these procedures will generally be adequate for blast loads exceeding the assumed load conditions (Ref 3).

Even with the simplifications presented in Reference 3, the computational procedures are complex and time-consuming. An automated procedure was required to give structural designers the capability of performing rapid analysis of the structural safety of blast-resistant walls and doors. The design parameters interact in a complex way since the procedure is both nonlinear and dynamic. From a design point of view an optimization procedure was required to minimize cost and maximize safety since blast-resistant construction has been reported to cost three to five times as much as conventional construction. Therefore, the first objective was to automate the analysis procedures for determining the structural response of plates having a bilinear stiffness representation and subjected to blast shock and gas pressures. Plates are the basic elements forming sidewalls, roofs, floors, and doors of cells designed to confine the effects of accidental explosions. The second objective was to provide an optimum design procedure that will automatically produce a least-cost design for a given geometry, material properties, and explosive weight for both feasible and nonfeasible starting points.

COMPUTER PROGRAM

The computer program was written in FORTRAN IV for use with Control Data 6600 series computers. The program is composed of four areas:

- 1. Blast Load Determination
- 2. Structural Analysis Parameters
- 3. Dynamic Response
- 4. Optimization

The blast-load determination is accomplished by subroutines BLA, PIC, SGRID, HBA, RATIO, GRID, GAS INTERP, EQUIV, HEDATA, ARDC, SHOCK, and TNT. The subroutines read the explosive weight and type and cell geometry, and the compute the equivalent spherical weight of TNT and the equivalent pressure loading using the geometry of the wall and charge location. Both the shock pressure and its duration and the gas pressure and its duration are calculated as in References 3 and 4. Using the duration and pressure data for both shock and gas, the program computes an equivalent triangular pressure loading for each part and adds both together to produce the resultant shown in Figure 1. The total impulse is then determined as in Reference 3.

The structural analysis is accomplished by subroutines SSTIFF, DOOR 1, DOOR 2, DOOR 3, DOOR 4 and DOOR 5. These routines compute the stiffness, resistance, and equivalent mass of the plate using input material properties as in Reference 3. Both flexure and shear are considered. Openings in plates are allowed as indicated in Figure 2c.

The <u>dynamic response calculation</u> is accomplished in subroutine RESP. The program determines the response of the plate modeled as an equivalent dynamic single-degree-of-freedom system with bilinear stiffness and the pressure loading shown in Figure 1. The solution technique is based on a Newmark iteration method.

When a thickness of sand is specified for composite construction (i.e., two plates with sandfill), the program computes the impulse capacity of the first plate using half the mass of the sand as acting with the wall as in Reference 3. Figures 6-38 and 6-39 of Reference 3 give the attenuation of the blast wave on sand for evaluation of the impulse capacity of the second wall.

The optimization of an initial design is accomplished in subroutines OPT, MINIMZ, PMINZ, DMINZ, GETE, SUMRY, TLEFT, and GCOMP. The methodology used is that of a penalty function with individual minimization sequences being accomplished by the Powell method (References 4,5,6).

PROGRAM INPUT

The program input consists of five or six cards per case. Additional cases can be grouped together. Two blank cards are used after the last case. The user's guide, contained in the program with comment cards, is given here to assist in understanding the input. Card format is 8F10.0 except as noted. Figure 2a is an input data sheet to be used in conjunction with Figures 2b and c, which show the slab geometry and orientation that must be followed. The input required for each card is described below.

CARD 1		
COL 2 COI 69	COL 68 COL 79	HEADING OPTIMIZATION 0 = NO OPTIMIZATION CALCULATION, 1 = OPTIMIZATION CALCULATION
COL 71.	COL 72	FLAC 1 = 0 FOR PRESSURE CALCULATION, = 1 FOR INPUT PRESSURE (see Card 3)
COL 73	COI, 74	FLAG 2 FOR TS OR Z: $0 = TS$, $1 = INPUT Z$
COL 75	COL 76	FLAG 3 FOR IMPULSE GRID: 0 = OMIT, 1 = GRIT
COL 77	COL 78	FLAG 4 0 = NO DOOR, $1 = DOOR$
COL 79	COL 80	FLAG 5 PRINT: DOOR EQUILIBRIUM ITERATION 0 = OMIT, 1 = PRINT
CARD 2		
COL 1	COL 10	WEIGHT OF ACTUAL EXPLOSIVE, LB
COL 11	COL 20	EXPLOSIVE NUMBER, SEE TABLE 1
COL 21	COL 30	EXPLOSIVE LENGTH/DIAMETER RATIO
COL 31	COL 40	PROJECTILE CASE WEIGHT/EXPLOSIVE WEIGHT RATIO

COL 41 COL 51 COL 61	COL 50 COL 60 COL 70 COL 80	AMBIENT PRESSURE PSIA (DEFAULT 14.69 PSI) AMBIENT TEMPERATURE, °C (DEFAULT 20°) ALTITUDE KFT (WHEN PRESSURE AND TEMPER- ATURE NOT SPECIFIED) EFFECTIVE IMPULSE FRACTION COMPOSITE CONSTRUCTION (see Ref 3)
CARD 3		
COL 1	COL 10	RA DISTANCE CHARGE TO WALL FT OR EQUAL IMPULSE PSI-MS IF FLAG 1 = 1.0
COL 11	COL 20	H WALL HEIGHT, FT
COI. 21	COL 30	EL WALL LENGTH, FT
COL 31	COL 40	HLIT HEIGHT CHARGE FT OR EQUAL PRESSURE PSI IF FLAG 1 = 1.0
COL 41	COL 50	ELLIT DISTANCE CHARGE TO LEFT SIDE WALL FT
COL 51	COL 60	CELL VOLUME FOR GAS PRESSURE, FT 2
COL 61	COL 70	CELL VENT ALEA FOR GAS PRESSURE, FT
COL 71		EQ I FOR FLOOR REFLECTION
COL 72		EQ 1 FOR ROOF REFLECTION
COL 73		EQ 1 FOR JEFT WALL REFLECTION
COL 74		EQ 1 FOR RIGHT WALL REFLECTION, OTHERWISE, EQ 0 FOR NO REFLECTION
CARD 4		
COL 1	COL 10	DYNAMIC YIELD STRESS, PSI
COL 11	COI. 20	PLATE THICKNESS, IN.
COL 21	COL 30	NSIDE NUMBER OF SIDES WALL FIXED BOTTOM SIDE FIXED
	2.0	
	3.0	
	4.0	4 SIDES FIXED
	5,0	SIMPLE SUPPORTED BEAM AT TOP
		AND BOTTOM
	6.0	FIXED BEAM AT TOP AND BOTTOM
	7.0	BEAM BOTTOM FIXED TOP SIMPLE
	13.0	3 SIDES SIMPLE, 1 SIDE FREE
	14.0	
COL 31	COL 40	PLATE HEIGHT IF NOT EQUAL TO H CARD 3, FT
COL 41	COL 50	PLATE WIDTH IF NOT EQUAL TO EL CARD 3, FT
COL 51	COL 60	ALLOWABLE DUCTILITY LIMIT FOR CPTIMIZATION
COL 61	COL 70	THICKNESS SAND, FT
COL 71	COL 80	E MODULUS OF ELASTICITY, PSI

CARD 5 1F OPTION = 1 ON CARD 1 COLUMN 73-74, OTHERWISE SKIP

COL 1	COL 10	z HORIZONTAL SECTION MODULUS/IN., IN. ³ /IN.
COL 11	COL 20	z vertical section modulus/in., in.3/in.
COL 21	col. 30	AVERAGE MOMENT INERTIA/IN., IN.4/IN.
COL 31	COL 40	DOOR WEIGHT TOTAL, LB

CARD 6

BLAST DOOR PARAMETERS

IF OPTION = 1 ON CARD 1 COLUMN 77-78, OTHERWISE SKIP

COL 1	COL 10	DOOR HEIGHT, FT
COL 11	COL 20	DOOR WIDTH, FT
COL 21	COL 30	DISTANCE FROM LEFT SIDE TO DOOR, FT
COI, 31	COL 40	DOOR REACTION, LB/IN.
OR		
COL 41	COI. 50	DOOR RESISTANCE FOR CALCULATION OF
		REACTION, PSI
COL 51	COL 60	DISTANCE TO FLOOR, FT

NOTE: All values are fixed point, except for reflection code and options.

The explosive number (Card 2) refers to the list of explosives in Table 1. This is used to compute explosive equivalence. The length/diameter ratio for an explosive sphere is 0.0, which gives a shape factor of 1.0. For an uncased explosive the case explosive weight ratio is 0.0. For sea level calculations, the ambient air pressure $P_{\rm amb}$, and temperature $T_{\rm amb}$, and altitude can be left blank and will default to 14.69 psi and 20°C. If the flag in the heading card is set to 1, the impulse, duration, and pressure will be read on Card 3. If the flag is left blank, the charge to wall distance, charge height, and distance from the left side will be read. If NSIDE is left blank, the program will sum the number of reflecting sidewall surfaces specified on Card 3. The separate use of NSIDE is helpful when a frangible wall is present, which creates a shock reflection but does not provide any support.

When optimization and composite construction are specified together, the program will optimize the design to resist the given or computed impulse. For the case when two walls are acting together—each resisting a portion of the impulse—it is necessary to specify the effective impulse to be applied to the wall under design. The total impulse is multiplied by the decimal number specified on Card 2. This procedure is based on similar work for concrete (Ref 4).

The NSIDE (see Figure 2b) conditions 1 through 4 are intended to be used to represent steel cell walls and roofs; NSIDE conditions 5 through 7 are steel plates spanning in one direction. The NSIDE conditions 13 and 14 are specifically intended to represent typical steel plate doors and pass-through windows.

STRUCTURAL OPTIMIZATION

The optimization problem consists of finding the least-cost structure that satisfies all the design constraints; or, stated in optimization terms: Find \vec{X} such that $M(\vec{X})$ is a minimum and

$$g_i(\vec{X}) \leq 0$$
 i = 1, 2, N

where \vec{X} = vector of design variables

N = number of design constraints

g = vector of design constraints

M = objective function

Specifically for this problem, the design variables selected are areas of steel reinforcement and thickness of concrete. The design constraints are the flexural and shear limits. The objective function consists of the costs of formwork and concrete flexural and shear reinforcement.

Fixed Variables

W = explosive weight

H = height

EL = length

h = height of explosive above floor

 ℓ = distance of explosive from left side of wall

= distance of explosive from wall

I = reflection code

f = dynamic yield stress

 $\mu = ductility$

Design Parameters, X

X = t (thickness of plate)

Constraints, g(X)

 $\delta(X) = \delta(\theta)$, maximum deflection

 $t \ge 0.05 \text{ minimum thickness}$

t ≤ 20 maximum thickness

The methodology (Ref 5 and 6) selected uses the unconstrained minimization approach. The problem is converted to an unconstrained minimization by constructing a function ϕ , of the general form

$$\phi(\vec{X},r) = M(\vec{X}) + P[g_1(\vec{X}), \dots, g_n(\vec{X}), r]$$

For this problem the interior penalty function technique was selected. This methodology is suitable when gradients are not available, and, because the method uses the feasible region, a usable solution always results. The objective function is augmented with a penalty term that is small at points away from the constraints in the feasible region but increases rapidly as the constraints are approached. The form is as follows:

$$\phi(\vec{X},r) = M(\vec{X}) - r \sum_{j=1}^{N} \frac{1}{g_{j}(\vec{X})}$$

where M is to be minimized over all \vec{X} satisfying g $(\vec{X}) < 0$, j = 2 ...N. Note that if r is positive, then, since at any interior point all of the terms in the sum are negative, the effect is to add a positive penalty to M(\vec{X}). As the boundary is approached, some g (\vec{X}) will approach zero, and the penalty will increase rapidly. The parameter, r, will be made successively smaller in order to obtain the constrained minimum of M.

Objective function, F

$$Cost = F = H \cdot EL \cdot t \cdot C$$

where C = volumetric cost of material

$$\varphi = F + r \sum_{j=1}^{N} \left[\frac{1}{g_{j}(\vec{X})} \right]$$

where r = penalty parameter.

The program requires a starting point in the feasible region before optimization can proceed. This is accomplished automatically by the program by incrementing the design variables until a feasible point is reached.

An algorithm which comprises the steps most commonly used is as follows:

- 1. Given a starting point X_0 , satisfying all $g_j(\vec{X}) < 0$, and an initial value for r, minimize ϕ to obtain X_{\min} .
- 2. Check for convergence of X_{\min} to the optimum.

- 3. If the convergence criterion is not satisfied, reduce r by $r \leftarrow rc$, where c < 1.
- 4. Compute a new starting point for the minimization, initialize the minimization algorithm, and repeat from step 1.

The logic diagram for the interior penalty functions technique is shown in Figure 3.

The minimization for $\phi(\vec{X},r)$ shown in Figure 3 is accomplished by a method developed by Powell using conjugate directions (Ref 5 and 6).

Powell's method can be understood as follows: Given that the function has been minimized once in each of the coordinate directions and then in the associated pattern direction, discard one of the coordinate directions in favor of the pattern direction for inclusion in the next m minimizations, since this is likely to be a better direction than the discarded coordinate direction. After the next cycle of minimizations, generate a new pattern direction and again replace one of the coordinate directions. This process is illustrated in Figure 4.

Figure 5 is a logic diagram for the unconstrained minimization algorithm. The pattern move is constructed in block A, then used for a minimization step (blocks B and C), and then stored in S_n (block D) as all of the directions are up-numbered and S_1 is discarded. The direction S_n will then be used for a minimizing step just before the construction of the next pattern direction. Consequently, in the second cycle, both X and Y in block A are points that are minima along S_n , the last pattern direction. This sequence will impart special properties to $S_{n+1} = X - Y$ that are the source of the rapid convergence of the method.

Figure 5 shows a block requiring a one-dimensional minimization of α^* of the function $\phi(\vec{X}+\alpha \; S_q)$. The one-dimensional minimization uses a four-point cubic interpolation. It finds the minimum along the direction S_q , where \vec{X} is the coordinate of the previous minimum. By trial and error it finds three points with the middle one less than the other two. It makes a quadratic interpolation and, then, a cubic interpolation. If the actual function evaluated at the new interpolated point is not sufficiently close to that of the preceding point, or if it is not sufficiently close to the interpolated function, then another cubic interpolation is made. The logic for this algorithm is shown in Figure 6.

APPROXIMATE COMPUTATION OF DOOR REACTION

It should be emphasized that this program is intended to assist in rapid approximate design and not detailed analysis. The basic procedures in References 3 and 4 and used herein have been found to be sufficiently accurate for simple geometries of beams and slabs without openings. Figure 7 compares deflections for a plate fixed on four sides and for a beam; the approximate solutions and the finite element solutions agree

within about 10%. However, the static shear procedures suggested in Reference 3 are seen to be substantially below dynamic shears (Figure 8); this is a limitation of the approximate procedures and is under current investigation.

A steel door attached to a concrete wall was examined using a finite element technique. Figure 9 shows the slab and door; Figure 10 shows the deflection of the door by the approximate procedure developed herein and the finite element procedure. There is some disagreement in deflection, especially when one considers the deflecting top support. It should be particularly noted that the deflecting support condition for actual doors on slabs (modeled correctly by finite element and assumed rigid by approximate solution) absorbs significant amounts of energy by rigid-body/door motion. Thus, the resulting center door deflection is reduced. The resulting dynamic shear around the door (transferred to the wall) is reduced from what would be computed for a nondeflecting plate using approximate dynamic plate theory (Figure 11). The alternatives are to use finite element analysis procedures or to modify dynamic plate theory. Finite element analysis is certainly the better approach; however, it is basically an analysis technique and is more difficult and expensive to use than the simpler approximate procedure. It is suggested that the shear calculated from approximate plate theory be adjusted by a constant for use as a door reaction required for input to wall design (Ref 4).

The maximum reaction occurs at the moment the slab first reaches yield. At this point the combination of load and resistance is maximum. Table 2 gives maximum dynamic reaction for a simply supported plate. For the case of one side free and three sides simple-supported, the b-dimension doubled may be used. The values of pressure P and resistance R are taken from the computer output at the time of yielding. The reaction values should be adjusted for support deflection. The value of 1.0 is suggested for nondeflecting supports and 0.5 for full deflecting supports as approximate factors. Once design has been finalized it is suggested that results be analyzed using a finite element analysis.

DISCUSSION

This program was developed to perform rapid design of steel plates used to form the sides and roofs of blast cells and also of steel plates used as doors. Provisions are included for use of plastic section modules for built-up doors; but optimization of such doors may not be performed because the weight-strength function is not defined.

In general, the methods used in the consister program follow Reference 3; consequently, the accuracy of both is the same. These are discussed in detail in References 3 and 4 and will not be presented here. The solution of the dynamic response equation of motion has been found to agree very closely with the response chart of Reference 3. Additionally, the solution covers a wider range and, thus, is more accurate in the

areas not defined by the response chart. When the loading is less than one hundredth of the natural period, the response is determined by impulse equilibrium. The basic dynamic model is limited to the primary response mode and does not consider higher modes.

The blast impulse computation is restricted to a geometry in which the slab's height-to-length ratio is greater than 0.2. A modification was made by the Naval Surface Weapons Center to the original Picatinny Arsenal Program to remove several minor problem areas, such as the location of the charge. The blast impulse has all the limitations associated with the original Picatinny programs that are caused by limitations in the test data. It assumes the charge is an equivalent sphere of TNT. Shape effects, explosive equivalence, and explosive casings are considered, but only in an empirical manner as a result of limited available data.

Example problems are presented in the Appendix.

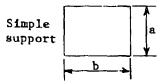
REFERENCES

- 1. J. O. Gill et al. "Preliminary report on the modernization of the Naval ordnance production base and application of hazard risk analysis technique," paper presented at the Fifteenth Explosive Safety Seminar, Department of Defense Explosive Safety Board, San Francisco, Calif., Sep 1973.
- 2. Arthur Mendolia. "A new approach to explosives safety," paper presented at the Fifteenth Explosive Safety Seminar, Department of Defense Explosive Safety Board, San Francisco, Calif., Sep 1973.
- 3. Departments of the Army, Navy, and Air Force. TM5-1300, NAVFAC P-397, and AFM 88-22: Structures to resist the effects of accidental explosions. Washington, DC, Jun 1969.
- 4. Civil Engineering Laboratory. Technical Note TN-1494: Optimum dynamic design of nonlinear reinforced concrete slabs under blast loading, by J. M. Ferritto. Port Hueneme, Calif., Jul 1977.
- 5. R. L. Fox. Optimization methods for engineering design. Addison Wesley, Reading, Mass., 1971.
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Table 1. List of Explosives

Explosive Number	Explosive Name and Composition
1	TNT
2	TNETB
3	EXPLOSIVE D
4	PENTOLITE (PETN/TNT 50/50)
5	PICRATOL (EXPLOSIVE D/TNT 52/48)
6	CYCLOTOL (RDX/TNT 70/30)
7	COMP B (RDX/TNT/WAX 59.4/39.6/1.0)
8	RDX/WAX (98/2)
9	COMP A-3 (RDX/WAX 91/9)
10	TNETB/AL (90/10)
11	TNETB/AL (78/22)
12	TNETB/Ai. (72/28)
13	TNETB/AL (65/34)
14	TRITONAL (TNT/AL 80/70)
15	RDX/AL/WAX (88/10/2)
16	RDX/AL/WAX (89/20/2)
17	RDX/AL/WAX (74/21/5)
18	RDX/AL/WAX (74/22/4)
19	RDX/AL/WAX (62/33/5)
20	TORPEX II (RDX/TNT/AL 42/40/18)
21	H6 (RDX/TNT/AL/WAX 45/29/21/5)
22	HBX-1 (RDX/TNT/AL/WAX 40/38/16/5)
23	HBX-3 (RDX/TNT/AL/WAX 31/29/35/5)
24	TNETB/RDX/AL (39/26/35)
25	ALUMINUM
26	MVX
27	RDX
28	PETN
29	TETRYL

Table 2. Four Sides, Uniform Load*



Strain	- /1	Dynamic R	eactions**
Range	a/b	V _A /b	ν _B /a
	1.0	0.07P + 0.18R	0.07P + 0.18R
	0.9	0.06P + 0.16R	0.08P + 0.20R
Flored	0.8	0.06P + 0.14R	0.08P + 0.22R
Elastic	0.7	0.05P + 0.13R	0.08P + 0.24R
	0.6	0.04P + 0.11R	0.09P + 0.26R
	0.5	0.04P + 0.09R	0.09P + 0.28R
	1.0	0.09P + 0.16R	0.09P + 0.16k
	0.9	0.08P + 0.15R	0.09P + 0.18R _m
Plastic	0.8	0.07P + 0.13R _m	0.10P + 0.20R
Plastic	0.7	0.06P + 0.12R	0.10P + 0.22R
	0.6	0.05P + 0.10R _m	0.10P + 0.25R _m
	0.5	0.04P + 0.08R _m	0.11P + 0.27R _m

^{*}Based on information from Ref 7.

^{**}P = pressure at time of yield, psi
 R = resistance, psi
 R_m = yield resistance, psi

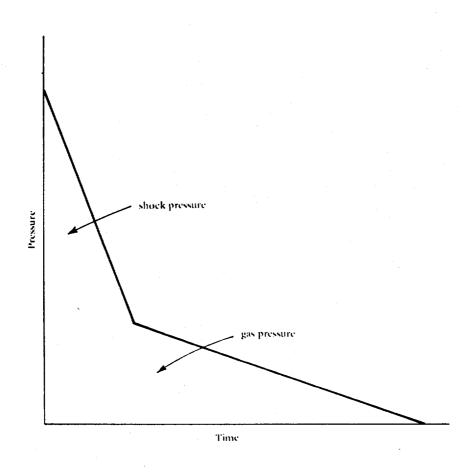


Figure 1. Equivalent pressure loading.

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1	W (Ib)	Expl No.	Vd Ratio	Case/Explo	P _{amb} (psia)	Tamb (°C)	Alritude (kft)	Pra	Praction I used	}	
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IJ	Door Height (ft)	Door Width (ft)	Dist to Left (ft)	Door Reaction (lb/in.)	n.) Door RU (psi)	Dist to Floor (ft)					T
•]
		Sieel stress (psi)					N Side				T
	SL	Thickness steel plate (in) Code		Z hor Plast	Plastic Z Section mod horizontal		l Bottom	fixed			
	₹	Place height if not equal to H (ft) State width if not equal to L (ft) Ductitiv Sand thickness (ft)	to L (ft)		Average I moment inertial Door weight (Ib)			2 sides fre. 2 free 3 sides fre. 1 free 4 sides fre. Simple beam H Frix Beam H 1 vix simple beam 3 sides simple, 1 free			
							14 4 sides simple	ыplc			

Figure 2a. Input data form.

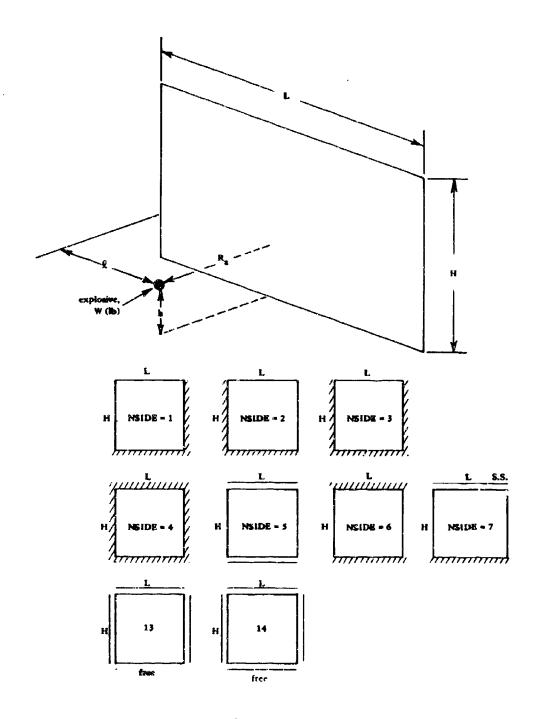
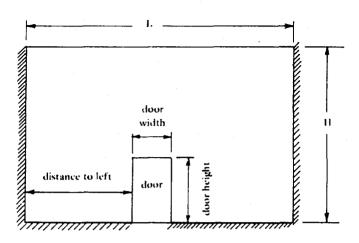
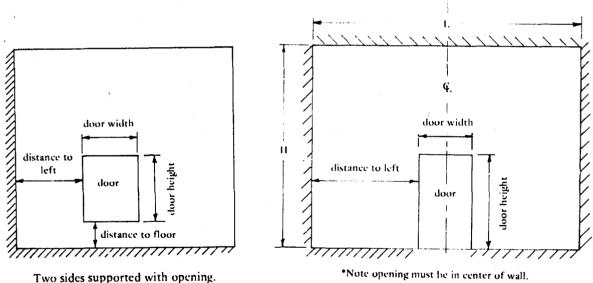


Figure 2b. Wall geometry.



Wall three sides supported with door.



Two sides supported with opening.

Wall four sides supported with opening.

Figure 2c. Plate geometry with opening for door.

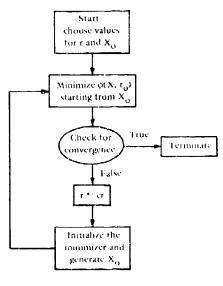


Figure 3. Logic diagram for interior penalty function technique.

Figure 4. Step process, Powell method.

- objective function

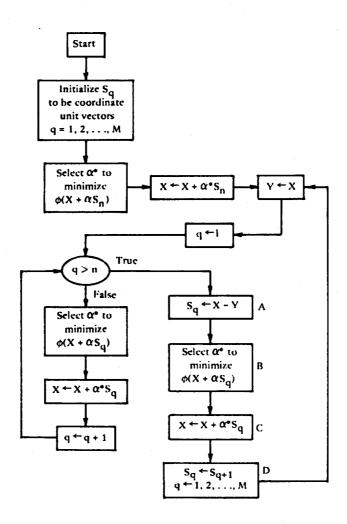


Figure 5. Logic diagram for minimization of $\phi(X)$.

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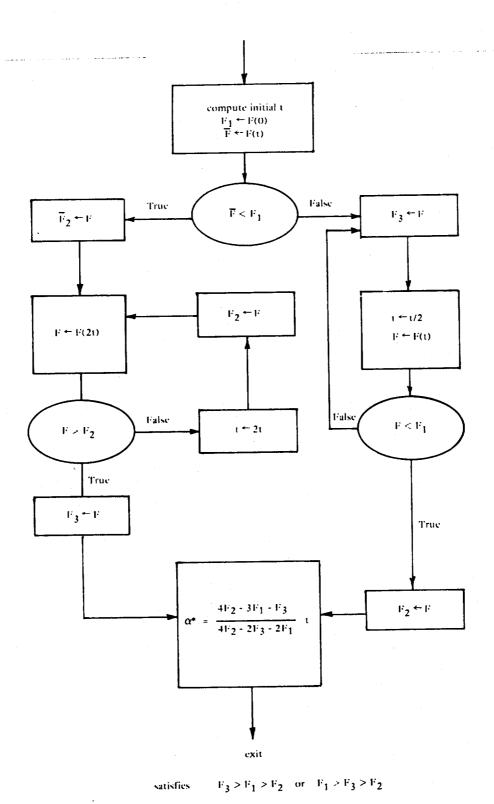


Figure 6. One-dimensional minimization algorithm.

GEL 50027

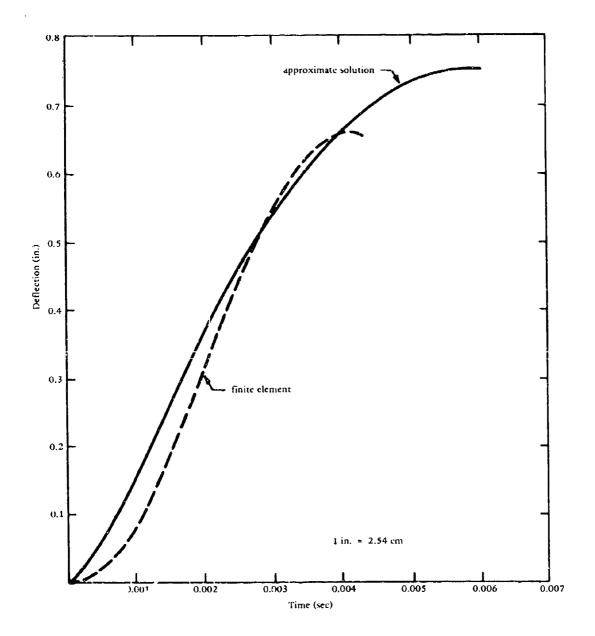


Figure 7a. Displacement history of 4×4 -ft (1.2 x 1.2-m) plate.

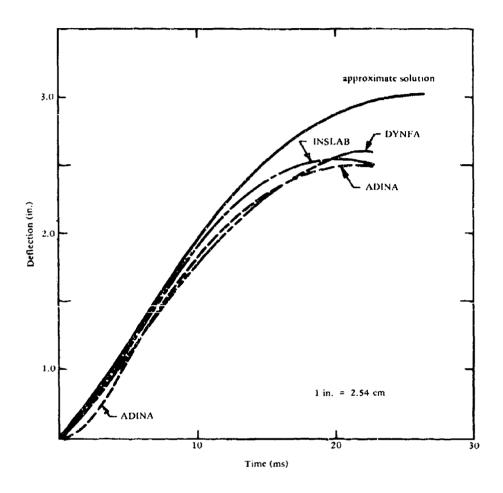


Figure 7b. Deflection of center, 10-ft (3-m) beam.

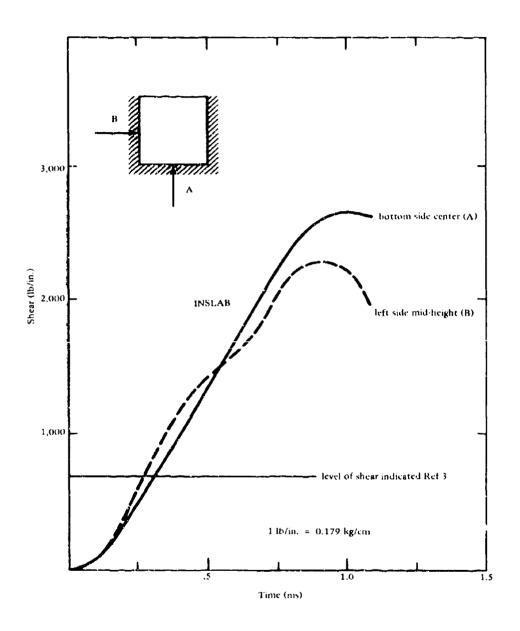


Figure 8. Shear in place.

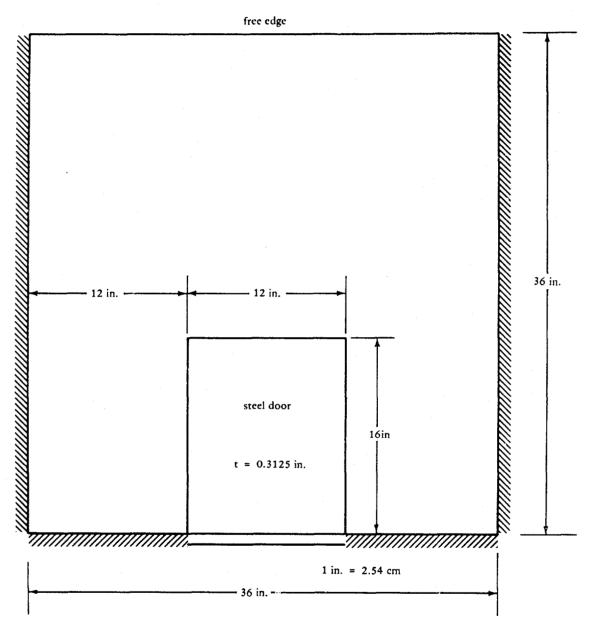


Figure 9. Geometry slab with door.

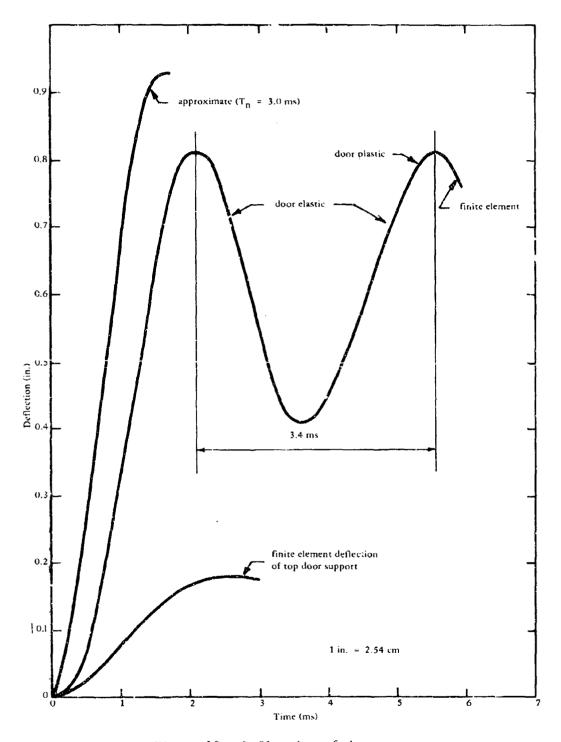


Figure 10. Deflection of door center.

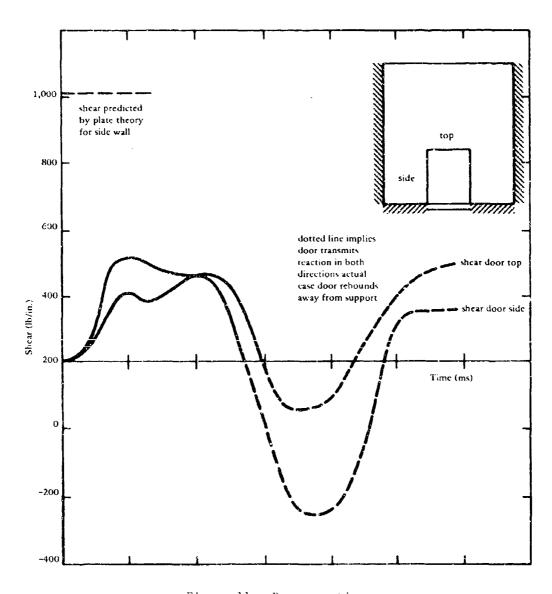


Figure 11. Door reaction.

APPENDIX

EXAMPLE PROBLEM 1

Design a door made of steel plate for the following:

- 1. Door Height = 6 ft
- 2. Door Width = 4 ft
- 3. Dynamic Yield Stress = 48,000 psi
- 4. Simple Support, Bottom Free
- 5. Allowable Ductility = 10

The door is contained in a wall 12 ft wide by 10 ft high. Side walls and roof are present to provide reflecting surfaces. The explosive is 10 lb Composition B uncased located 3 ft from the wall, 5 ft from the left side, and 3 ft above the floor. Figure A-1 shows the example problem input form, and Figure A-2 shows the output.

EXAMPLE PROBLEM 2

Design a steel plate window:

- 1. Height = 3 ft
- 2. Width = 3 f.t.
- 3. Dynamic Yield Stress = 48,000 psi
- 4. Simple Support, Four Sides
- 5. Allowable Ductility = 10

The window is located on the wall of a cell 12 ft long by 10 ft high. A 12-1b TNT explosive with length-to-diameter of 2.5 and case-to-explosive of 1.2 is located 3 ft away from the wall, 5 ft from the left side, and 3 ft above ground. The cell has two sidewalls and a floor. No roof reflecting surface is present. Figure Λ -3 shows the example problem input and Figure Λ -4 gives the output.

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Figure A-1. Computer data format for example problem 1.

COMP B (RDX/INI/WAX,59.4/39.6/1.0)

EXPLOSIVE PROPERTIES....CHARGE WEIGHT(LB) # 10.00
NUMBER EGWT EFORM EXPLOSIVE COMPOSITION BY WEIGHT
KCAL/G C H N O AL
7 1.100 .004330 .252 .026 .298 .424 0.000

PAMB(PSIA)# 14.69 TAMB(C)# 20.00

SHOCK WAVE CALCULATION

		CHARGE MEIGHT ADJUSTMENTS	တ
	10.00	ADJUSTED WT(LB TNT) #	11.00
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	, O.	CHARGE SHAPE FACTOR #	1.000
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	20.00	DISTANCE SCALE FACTORE	9677
ALTITION (KEL)	0	TIME SCALE FACTOR #	. 4535
	•	NORMAL REFL FACTOR #	7.526

DESIRED DISTANCE(FT) # 3.000 (CM) # 91.44

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IME AF	L0810	(MSEC)	61	369	424	478	5	86	40	769	0672	03

IMPULSE (PSI, MSEC) -INCIDENT # 53.86
REFLECTED# 405.3

EDING PAGE

•••••CAUTION--CONTACT SURFACE HAS ARRIVED.

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œ	433.5	411.8 381.6	394.1	379.3	368.6	362.6	361.5	362.6	364.7	367.8
8 0	448.8 369.4	381.7	392.4 398.9	374.7	362.1	354.9	353.2	354.4	357.0	361.3
7	369.5	423.8	395.9	375.4	361.3	353.2	351.0	5.55	355.1	360.4
	523.1 372.0	433.8	# 20 # # 05 # #	380.8	366.0	357.5	354.8	355.7	357.9	363.0
so.	543.9 378.1	346.2	414.6	39≥.8	378.2	369.7	366.5	366.6	367.4	370.9
3	560.0 388.8	461.5 398.2	432.4 421.5	412.9	399.8	391.8	387.9	386.4	384.5	384.8
ы	571.3 405.5	482.2	4.954	445.7	438.8	432.9	427.1	419.6	412.2	6.907
Q u	615.6	578.8 041.1	511.8	513.8	512.6	508.9	501.4	488.6	6.997	508.0
	4.609.4 506.7	650°4	730.2	838.8	632.7	1.659	7559	615.6	6.89.3	586.9
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מבויים אט מסקס	5.72156 HSEC	184 00206 1851 8M ISA85.077
10LSE		I P P E S S U R E S U R E S S U R E S
101al IMPULSE	DURATION OF LOAD	FICTITIOUS PEAK FEFECTIVE IMPULSE FS DYNAMIC ABBOO. PL THICK S. SPT CODE 13.0 D H O DUC 1 SAND 10.0

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72.00 LENGTH	VERTICAL MOMENT	VERTICAL JMENI HORIZONTAL MOMENT	HORIZONTAL MOMENT	. 0000 72	34.7913	243.2242	245.6 6	237,0305	.8885	273.75	72.466
HEIGHT	POSITIVE	POSITIVE	NEGATIVE	×	>-	D	3	0 3	×	¥	TAGG

8.8850 ALLUWABLE MAX DEFLECTION

00.00 MASS 996.235
LOAD 153.902
DURATION 5.722
RESISTANCE 243.225
STIFFNESS 273.749
GAS PRESSURE 0.000

	NOW FROM FROM	> FILE CONTRACTOR			
27.60					
7007		֓֞֜֜֜֜֜֜֜֜֓֓֓֓֜֜֜֜֜֓֓֓֓֜֜֜֜֓֓֓֓֡֓֜֜֜֜֓֓֡֓֜֜֡֓֡֡֓֜֜֡֡֡֡֓֡֓֡֡֡	2 6	no.,	30
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6097	N	51	90	4.592	4
9934	0	59	2	3.160	I C
. 452586	.1378	.0667	.0163	141,7281	077
0583	135	7.4	2	40.295	
5907	N	8	2	8.863	
61232	130	88	8	37.431	
6556	127	9.5	33	35,999	7.70
71881	124	0	39	34.567	716
77205	121	0.8	77	33,134	040
2530	Œ	77	6	31.702	410
87854	1.5	2	057	30.270	444
93179	1.1.1	26	6	28.838	7.504
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00117	078	72	137	15.948	7,494
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57073	990	77	165	11,651	5,351
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.67722	ις: (30	~	185	08.786	0.849
7 3047	KU M	76	196	07.354	3,665
.78372	67	96	90	05.922	6.523
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12069	070	5	227	3.058	2.348
. 44 54 5 6 1 7 6 6	36	9	238	1.625	5.309
0/966	M	S	249	193	8.297
04994	5	0 7	260	8,761	1,309
61501°	⊘	208	271	7.329	4.341
.15643	€	500	82	5.896	7.391
0968	1.4	10	93	4.464	0.454
26292	00	21.7	5	3.032	3.527
31617	C.S	211	9	1.600	6.607
36941	000	21	27	0.168	9.590
42266	70	211	Ę	8.735	2.772
47590	C	211	9	7.303	5. AS

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Figure A-2. Continued
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MATURAL PERIOD

MAXIMUM DEFLECTION

TIME TO MAXIMUM DEFLECTION

OURATION/MATURAL PERIOD

LOAD/PESISTANCE

ELASTIC DEFLECTION LIMIT

XLIMIT

TOTAL COST

TOTAL COST

TOTAL

COUNT

0.00
```

X)S ARE 2.000000E+00 G)S ARE 8.231998E+00 1.950300E+03 1.800000E+01 6.923036E+00 R # 1.47844665E+03
ITER # 0 P # 2.37120000E+03 08J # 1.18560000E+03
ITER # 3 P # 2.30497843E+03 08J # 9.31358665E+02
X)S ARE
1.571116E+00

G)S ARE 1.014689E+01 1.521116E+00 1.84288AE+01 8.412525E+00

FUNCTION CALLS # 45

8.156445E-01

6)8 ARE 1.530044E+01 7.656445E-01 1.918436E+01 3.090083E+00

FUNCTION CALLS # 60

XNEXT(1) # 7.385035E=01

```
083 m 4.377849175+02
      в и.75907474E+02
в и.75857728E+02
# 1.47844666E+01
                  2
                                         7.369159E-01
                               X)S. APE
          TER #
```

1.547552E+01 6.869159E+01 1.926308E+01 9.376134E+01 G)S ARE

ار در FUNCTION CALLS E

7.1201976-01 XNEXT(1) #

```
083 m 4.22085264E+02
                 # 4.26103978E+02
       P # 4.53479894F+02
R # 1.4784466E+00
                                         7.187989E-01
                              X)S ARE
           TER #
```

1.545027E+01 6.687989E-01 1.928120E+01 3.045773E-01

11 FUNCTION CALLS #

G)S ARE

XNEXT(I) =

7.130698E-01

083 m 4.22707772E+02 083 m 4.22807189E+02 P # 4.24577319E+02 R # 1.47844666E+01 7.132375E-01 0 N ITER B 8311

1.543553E+01 6.632375E-01 1.928676E+01 9.707400E*02 G) S ARE

FUNCTION CALLS

XNEXT(I) # 7.114788E-01

273 TOTAL FUNCTION CALLS #

Figure A-2. Continued

Figure A-2. Continued

.6817 .2761

	8	••••	0. BB . C	3.000		46000	7.000	0.427									1			780	0.780	7 9 0	7.780	7.00	7.00	•	0.780	0.789	0.7.0	0.780	0.780	0.780	0.780	0.780	0.780	0.780	0.180	0.78	0.780	0.780	0.780	7.8	0.780	0.780	0.78	0.780	0.780	
, 11, 344,			6000.40I	101.101		666- C.C.	^		AV.00.40			3	. 897		4. 9.12		5.787		104.	•	4.4.7	000	4.971	0.430	905.5	1 4 9 . 0	. 34	40	.000	.000	•	600.	000.	, n 3 n	.000	000.	.000	. 300	000.	.000	000.	0000.	000	000	000	.000	000	000.
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		٥	200	•	084.0
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5542	C	603	070.	000.	0.780
0952	9	91	.585	.000	9.780
2990	4	7	.693	000	780
8371	086	555	. 797	000	780
7031	86	53.B	899	000	780
5790	•	525	. 997	000.	0.780
6677	086	506	.093	.000	0.780
1 32092	•• 0869	1067.	8.1858	00000	2007.0E
1918	\$	73	.275	.000	0.780
062ª	86	57	. 361	000.	0.780
9337	86	7	777.	000	0.780
8046	8	25	. 525	000.	0.780
6756	86	0.8	.602	.000	0.780
5465	86	92	.676	.000	0.780
4174	8	376	747	. n n n	0.780
2884	ę P	9	.816	.000	0.780
1593	A 6	343	.881	.000	0.780
0303	8	327	.943	.000	0.780
9012	8	=	.002	.000	0.780
1721	D L	295	.05A	.000	0.780
6431	A O	278	.111	000.	0.789
5140	4	262	.160	.000	0.780
3850	8	40	.207	.000	0.0
2559	86	230	. 251	.000	0.00
1268	•	213	.292	.000	0.780
9978	4 0	197	.330	000.	0.780
8687	0.96	-	.364	.000	0.780
7397	S.	165	. 396	.000	0.780
6106	8	148	.424	.000	0.780
4815	8	32	.450	.000	0.780
3525	9	9	. 473	.000	0.780
2234	9	00	267.	.000	0.780
7760	e S	83	.509	000.	0.780
9653	80	67	. 522	.000	0.780
8362	ď.	2	.532	.000	0.780
7072	96	35	.540	.000	0.780
5781	\$	18	775.	.000	0.780
077	9	0.5	.545	000.	0.780

NATURAL PERIOD	33.693969
MAXIMUM DEFLECTION	9.545575
TIME TO MAXIMUM DEFLECTION	16.704911
DURATIUN/NATURAL PERICO	.169810
LOAD/RESISTANCE	5.000020
IC DEFLE	2.497604
1.4343 TIME TO YIELD 3.92897349	
8.00	

Figure A-2. Continued

G. Z.			Format F	Format For Computer Program SDOUR	UR.		шишпаф	1 04 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Door it
_	Heading					·	-	_	
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	w (lb)	Expl No.	Vd Ratio	Case/Explo	Pamb (pus)	Tamb (^O C)	Altitude (kft)	Praction 1 used	7
~	12.	. :	2.5	1.2					
	R _k (ft)/1 (psi-ms)*	(y) H	L (ft)	h (ft/Po (psi)*	1 (ft)/t _{to} (ms)*	Cell Vol (ft.³)	Vent Area (ft ²)	FRLR	
~	mi	10.	12.	ĸ.	5.			1 0 1 1	
	FS (p4)	TS (in.)	N Side	(t)	DEL (ft)	7	T Sand (ft)	-	
-	48,000.	-2.		۲,	3.	10.			
	Z hor	Z wer	AICAV	WDR					
~									
	Door Height (ft)	Duor Width (ft)	Dist to Left (ft)	Dux Reaction (lb/in.)	Iker RU (pu)	Dist to Fluor (ft)			
•					:				
	7.5 S.N. S.N. S.N. S.N. S.N. S.N. S.N. S.	Steel stees (ps) This kness steel plate (in.) Code Hate bright if not equal to H (ft) Plate with if not equal to L (ft) Ductility Sand thickness (ft)	. t (f)	Optom 17.2 = 1 Z. hor — Plastic Z. Section Z. ver — Plastic Z. Section AICAV - Average I momen WDR — Dwor weight (1b)	172 - 1 Plaste & Section med horizontal Plaste & Section Mod verteal Average I moment mertia [Soor weight (Ib.)		Solic	s Sade Hottom fixed 2. 2 ades fix. 2 free 3. 3 ades fix. 3 free 4. 4 ades fix. 3 free 5. 5 mople beam 11 6. 1 xx keem 11 7. 1 xx keem 11 7. 1 xx keem 11 8. 3 ades umple. 1 free 14. 4 ades umple.	

Figure A-3. Input for example problem 2.

Z

EXPLOSIVE PROPERTIES....CHARGE MEIGHT(LH) # 12.00
NUMBER EGAT EFURY EXPLOSIVE COMPOSITION HY AEIGHT
ACAL/G C H N O AL
1 1.000 -.079400 .370 .022 .185 .423 0.000

RANGE OF EXPERIMENTAL DATA. RANGE OF EXPERIMENTAL DATA. PAMB(PSIA) # 14.69 TAMB(C) # 20.00
....CHARGE SHAPE CORRECTION IS CRUDE. PSI EXCEEDS
....CASE *EIGHT CORRECTION IS CRUDE. PSI EXCEEDS

SHOCK MAVE CALCULATION

3163 3.703 .7109 1.000 i.000 8.650 31,59 CHAPGE AEIGHT ADJUSTMENTS PRESSURE SCALE FACTORS DISTANCE SCALE FACTORS TIME SCALE FACTOR ADJUSTED WILLS INT) CHARGE SHAPE FACTOR CASE VENGET PACTOR NORMAL REFL FACTOR HE ENERGY FACTOR 2.500 1.200 14.69 20.00 12.00 CHAMBER PRESSURE(PSIA)# CASE/CHARGE MT RATIO CHARGE WEIGHT (LB) INPUT PARAMETERS EXPLUSIVE NUMBER CHAMBER TEMP(C) ALTITUDE (KFT)

DESIRED DISTANCE(FT) # 3.000

OVERPRESS NORM REFL 696.8 449.0 276.6 153.7 64.82 8254 2603 1065 1640 (PST) INCIDENT CVERPRESS 31.98 7.494 684.3 189.6 80.56 51.91 301.0 (PSI) 123.1 TIME AFTER SHUCK ARR 1131 .2826 4525 .3392 (M8EC) .2261 1696 3957 5088 TIME AFTER EXPLUSION .7092 .4831 (MSEC) .2004 .3135 .3700 .5396 .6526 . 4265 .5961

IMPULSE (PSI, MSEC) -- INCIDENT # 107.9 REFLECTEUR 933.1

Figure A-4. Output for example problem 2.

CAUTIUNCONTACT SURFACE HAS ARRIVEU. DATA ARE CRUDE BEYOND I(MSEC) AFTER SHUCK ARRIVALE 37.1725E-03	HAS ARKIVED. T(MSEC) AFTER	SHUCK ARKIN	AL 37,1725E-03
DISTANCE OF CHARGE FUUM BLAST WALL Charge reight Blast Wall Height		# # # # # # # # # # # # # # # # # # #	3.00 31.59 10.01
BLAST WALL LENGTH HEIGHT OF CHARGE ABOVE GROUND MIN. DIST. BETWEEM CHARGE + ADJ. WALL REFLECTION CODE		• • • 	12.00 3.00 5.00 1.0 1

749.25 PSIANS	4.42317 MSEC	338	744.25PSI MS							
	F LOAD	PEAK PRESSUPE	IMPULSE	u8000.00	2,00	14.00	3.00	3.00	10.00	-0.00
TOTAL IMPULSE	DURATION OF LOAD	FICTITIOUS PEAK	EFFECTIVE	FS DYNAMIC	PL THICK	SPT CODE	T	0	000	T SAND

HEIGHT	1 36.00	2	LENGTH 36	36.00
OSITIVE	VERTICAL MO	E SUBSTITUTE OF	48000,00	
POSITIVE		MOMENT	48000,00	
1-4		MOMENT	48000.00	
×	•			
>-	18.00			
RU	898.89			

.2783 3194.19 822.04

		335	- u	747	של אל היי	070	957	194	0.777	3.703	6.967	0.564	4.489	8,736	3.300	8.171	3,345	A.813	4.569	0.603	. 912	3.483	908.0	7 . 361	74.04.00	0.0AU	7.949	26.112	797.7	115.994	1.691	0.546	9.545	178.5804	7.938	7.30R
	0407.	118 147	14 97	35.50A	34.324	33.050	31.775	30.501	29.227	27,953	26.678	25.404	24.130	25,855	21.581	20.307	19.032	17.75A	16.484	15.210	13,935	12.661	11,387	21.000	000.CO	086.90	05.015	03.741	02.467	01.192	90.018	98,644	97,369	296.0954	24.30	93.546
	DISPLACEMENT	000	0	000	00	0	0	~	03	70	000	9	007	606	2:	210	~ :	510	17	5 6	2 6	2 1	7 P	200	2 6	3	036	39	4.7	770	77	020	53	\$ 0.00 B	, C	<u>-</u>
	VELOCITY	.003	10	17	23	30	037	7 M	0.50	0.56	6	9 1	0.75	9 0	200	5 6 6	\$ 6 6 6	7 0	0 -	• ·		3 0	7 7	7 7	n c	146	150	-7	Œ	-	7	~	0	1725	3 .	o.
ይ 3 3 3	ACCELERATION	. 4112	4091	90	0.3	00	.3964	€.	6	De: Geri	9) / S	304	7	200	9 t	7	7 0	0 0 0		2 *	- 0	100	9	676	23.A	227	216	7	192	80	00 (55	6 C C C C C C C C C C C C C C C C C C C	> 1	
LCAD 338.78 CURATION 4.42 RESISTANCE BBA.88 STIFFNESS 3194.196 GAS PRESSURE	1146	.008319	0249	.041593	585	748	-	- 8	1247	7 17 17	1580 1580		7 7 7 7	7 1) -) -	7 T	0/CJ		1071	770	1 4 C - O F C	7 1 2	747	606	076	N	607	573	741	90 C	5 L O	2.402.0 2.402.0	- 1 - 1 - 1 - 1		100	

Figure A-4. Continued

06.77	14.			8/0°C9	47.455	25.65	65.062	74.908	84.761	909.76	04.437	14.256	63.445	760.00	42.430 42.430	140.30	71.744	81.004	90.142	99.147	09.006	16.709	25.245	33.604	41.776	49.751	57.517	65.067	72,390	79.078	486.3209	24.00	700.70	11.076	16.571	21.774	26.677	31.275	15.561	39.531	43.179	46.500	49.00	52,139	54.049	55.414
92.272	90.998	80.724	077 WW	70.00	2 0 0 M	701.00	といこ ひい		1 / C · O d		70.500	0000	70.01	74.413	73.158	71.883	70.609	69.335	68.060	66.785	65.512	54.237	62.963	51.689	60.415	59.140	57.866	59.895	59.317	54.043	252.7692	2000	470,67	47.672	46.397	45.123	43.849	42.574	41.300	40.026	38.751	37.477	36.203	34.920	33.654	32,380
79	067	070	074	7 6	0.70	9	2 4		000	ט נו ס ר	ר מ	-	70	107	2	113	116	119	122	125	127	130	53	35	138	140	F 7	145	147	150		5.4	5.00	160	161	163	164	166	167	168	170	171	A	U.	~	27
α.	8	£	83	6	9		ישי	שי	: ur	יי מ	200	A 4	20	181	79	177	175	173	171	168	166	163	159	156	152	100	1 45	771	95.	25.	C 000	117	112	107	102	96	9	S S	7	73	57	50	2	90	7	35
0		7	4	S	5	. 7	, ,	0	0.0		0.4	057	070	. H C	160.		123	.135	. 149	161	. 173	1.85	- 67	6 02.	0 2 5 0 7 5 0 7 5	. 231	242		300	3 C	1 00 00 00 00 00 00 00 00 00 00 00 00 00	305	.311	. 320	.328	336	775.	35.	35A	364	370	375	381	8.5	000	76
0726	2389	4053	5717	7381	7706	0708	277	000	80.00	7447	7504	0690	354	4018	5685	7345	6006	0673	2337	0000	2664	7328	98991	00655	02319	58680		01510	4 4 4 6 9	00001	1.139655	15629	17292	18956	20620	22284	75767	72011	27275	28939	30602	32266	33930	35593	37257	58961

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Figure A-4. Continued
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		.0288	. 1747	.106	
1.439126 1.425163 1.425163	4034 4057	. 0155	1707	28,557	
•	2100	0200	.1756	224.0089 226.0089	
NATURAL PERIOD	3.187478				
MAXIMUM DEFLECTION	.17561A			•	
TIME TO MAXIMUM DEFLECTION	1.472400				
DURATION/NATURAL PERTUD	1.387672				
LOAD/RESISTANCE	.381133				
ELASTIC DEFLECTION LIMIT	.278283				
COLAL COST 444.60					

554,0311 559,2961 560,2067 569,7606 569,9559

2.000000E+00 X)S ARE

G)S ARE 2.607216E+00 1.950000E+00 1.800000E+01 4.612382E+00

08J # 4.446000005+02 P # 8.89200000E+02 R * 3.80411425E+02 1.3232576+00 0 M ITER #X)S ARE

G)S ARE 3.615606E+00 1.273257E+00 1.867674E+01 4.197567E+00

9 FUNCTION CALLS #

08J = 2,94159923E+02 P # 3.45657824E+02 R # 3.80411425E+01 8.9213256-01 ITER # X)S ARE

```
3.273839E+00 8.421325E+01 1.910747E+01 1.823227E+00
G)S ARE
```

11 FUNCTION CALLS

T L

XNEXT(1) = 8.161653E-01

08J = 1,81433536E+02 08J = 1,80849350E+02 P # 1.93941A35E+n2 P # 1.93944567E+02 R = 3.80411425E+00 X)S ARE ITER #

8.135373E=01 G)S ARE

2.640894E+00 7.6353775-01 1.918646E+01 5.875754E-01

FUNCTION CALLS

7.886834E-01 XNEXT(I) #

083 x 1,75324312E+02 P m 1.80636195E+02 P m 1.79129860E+02 R 8 3.80411425E-01 7.937563E-01 0 ~ X)S ARE ITER # ITEP

2.415064E+00 7.437563E+01 1.920624E+01 1.912539E+01 G)S ARE

67 FUNCTION CALLS

XNEXT(I) #

7.875010E-01

08J = 1,750614696+02 # 1.75803414E+02 R # 3.80411425E-02 **a a** 7.877112E-01 ITER # X)S ARE TER 3

Continued Figure A-4.

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Figure A-4. Continued
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2.338819E+00 7.377112E-U1 1.921229E+U1 6.119876E-02 G)S AKE

10 FUNCTION CALLS .

7.857995E-01 XNEXT(1) #

271 TOTAL FUNCTION CALLS #

09J # 1,7468323E+02 PF = 1.7579960E+02 ITER #

X+S ARE

2.314746E+00 7.357995E-01 1.921420E+01 1.993667E-02 7.857995E-01 G)S ARE

LENGTH 3.00 10.00 46000.00 14.00 3.00 36.00 FS DYNASIC PL THICK SPT CODE U DUC 1E1611

7409.77 7409.77 POSITIVE VERTICAL MOMENT NEGATIVE VERTICAL MOMENT POSITIVE HORIZONTAL MOMENT NEGATIVE HURIZONTAL MOMENT 18.00 .7083 193.75 322.94 19.00

ALLOWABLE MAX DEFLECTION

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322,981 338,785 4.423 137.218 193,734 GAS PRESSURE DURATION RESIBTANCE STIFFNESS DURATION LOAD

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678	373	7	N	3.798	764
705	3.5	70	•	8.415	. 425
733	196	5	85	33,033	.877
760	154	5	27	17.650	.981
788	90	5	73	32.267	966.
815	5 6 5	ī	23	76.885	.579
37843	515	9	75	11.505	.785
94870	35.5	2	3	56.120	.568
01898	513	39	8	50.737	. 980
68925	091	7	550	55.355	.671
15952	SO	70	Ξ	26.01	.888
22980	12.0	3	78	14.590	. 491
30007	315	2	12.5	39.207	.218
37035	900	975	=	33,825	.218
4000	33	966	83	20.442	.218
51090	. 6	0.15	354	23.059	.218
5 A 1 1 7	2	033	26	17.671	.218
65145	3	5	0	12.294	.218
72172	2	990	74	6.912	.218
5612	661	8	5	01.529	.218
86227	6	760	327	96.147	1.218
93254	9	106	707	90.764	7.218
00282	149	117	48	85.385	7.21
07309	,	127	568	10.999	1.218
14337	1 1	136	.641	74.617	7.21
21364	60	143	.72	69.231	1.5.1
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35419	90	15	.883	SA.460	7.21
.42447	5	150	96	53.086	7.21
.4947	03		70	47.70	1.51
.55501	5		12	42.32	7.21
,63529	000			36.93	7.21
.7055	0		. 29	31,55	7.21
.7758	037		.37	6.17	7.21
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.9866	.080		9.	0.020	7.21
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.1272	-		.77	9.56	7.21
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NATURAL PERTOD	8.112700
MAXIMUM DEFLECTION	4,768063
TIME TO MAXIMUM DEFLECTION	4.254429
DURATION/NATURAL PERIOD	.505216
LOAD/RESISTANCE	2.468952
ELASTIC DEFLECTION LIMIT	.708261
TIME TO VIELD 1, 26494062	
XLIMIT 174.68 TOTAL COST 174.68 COUNT 276.00	·

Figure A-4. Continued

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